

Force

- **Peak: 744 - 1860 N**
- **Continuous: 137 - 276N**

Maximum Velocity

- **Up to 5.3 m/s**

Feedback

- **Built-in position sensor**
- **1V pk-pk sin/cos**
- **25 micron repeatability**

Range of motion

- **33~318 mm**

Dimensions

- **W x H: 70 x 122mm**
- **Rod diameter: 38mm**

Applications

- **Packaging**
- **Material Handling**
- **Automated Assembly**
- **Bio-medical**

The OEM advantage

- **Reliable and cost-effective**
- **Flexible position control**
- **High speed and acceleration**
- **Clean, quiet operation**
- **No maintenance or adjustment**



The ServoTube Actuator is an optimal solution for industrial position control. Faster than a ballscrew with the clean reliability of a linear forcer, ServoTube is a cost-effective alternative to air cylinders in applications requiring greater flexibility and control.

The ServoTube Actuator incorporates an IP67 rated forcer and a sealed stainless steel thrust rod enclosing rare-earth magnets. Four models deliver a continuous force range of 137~276 N (31~62 lb) with peak forces up to 1860 N (418 lb). Nine stroke lengths are available from 33~318 mm.

The patented magnetic design of ServoTube generates 25 micron (0.98 mil) repeatability and 400 micron (16 mil) accuracy from a non-contact, integral position sensor. No external encoder is required. Position output is industry standard 1V pk-pk sin/cos signals.

An internal dry bearing provides clean, quiet, maintenance-free performance. Life expectancy far exceeds typical ballscrew solutions.

The ServoTube Actuator is ideal for push/pull/lift material handling, packaging and automated assembly applications. ServoTube accepts a range of industry standard accessories for simple mechanical integration.

Flexible mid-stroke position control is simple with Xenus - a matched, self-tuning indexer complete with plug-and-play cabling. Simply select your ServoTube model number and the system comes up tuned and ready to run. Clear diagnostics make system commissioning easy. Fill in the blanks to define position, velocity and acceleration.

Xenus interfaces easily to PLC's and features CANopen network connectivity.

ELECTRICAL SPECIFICATIONS

FORCER TYPE	3804		3806		3808		3810		units
	S ⁽¹⁾	P ⁽¹⁾							
Peak force @ 25°C ambient for 1 sec	744	372	1116	558	1488	744	1860	930	N
Peak current @ 25°C ambient for 1 sec	20		20		20		20		Apk
With 25 x 25 x2.5cm heatsink plate									
Continuous stall force @ 25°C ambient ⁽²⁾	137.3		186.9		232.1		276.2		N
Continuous stall current @ 25°C ambient	2.61	5.23	2.37	4.74	2.20	4.41	2.10	4.20	Arms
	3.69	7.39	3.35	6.71	3.12	6.23	2.97	5.94	Apk
Without heatsink plate									
Continuous stall force @ 25°C ambient ⁽²⁾	120.1		168.2		212.7		255.0		N
Continuous stall current @ 25°C ambient	2.28	4.57	2.13	4.27	2.02	4.04	1.94	3.88	Arms
	3.23	6.46	3.01	6.03	2.86	5.72	2.74	5.49	Apk
Force constant (sine commutation)	52.6	26.3	78.9	39.4	105.2	52.6	131.5	65.7	N/Arms
	37.2	18.6	55.8	27.9	74.4	37.2	93.0	46.5	N/Apk
Back EMF constant (phase to phase)	43.0	21.5	64.4	32.2	85.9	42.9	107.4	53.7	Vpk/m/s
Fundamental forcer constant	14.54		17.80		20.56		22.99		N/√W
Eddy current loss	3.7		3.7		3.7		3.7		N/m/s
Sleeve cogging force	7.3		4.2		8.3		5.6		+/-N
Resistance @ 25°C (phase to phase)	6.77	1.69	10.16	2.54	13.54	3.38	16.93	4.23	Ohm
Resistance @ 100°C (phase to phase)	8.73	2.18	13.10	3.27	17.45	4.36	21.82	5.45	Ohm
Inductance @ 1kHz (phase to phase)	8.52	2.13	12.78	3.19	17.04	4.26	21.30	5.32	mH
Electrical time constant	1.26		1.26		1.26		1.26		ms
Maximum working voltage	380		380		380		380		V d.c.
Pole pitch (one electrical cycle)	71.2		71.2		71.2		71.2		mm
Peak acceleration ⁽³⁾	250	125	313	156	357	179	391	196	m/s ²
Maximum speed ⁽⁴⁾	4.7	4.9	3.8	5.3	3.1	4.9	2.6	4.4	m/s

Notes: -

⁽¹⁾ S=series forcer phases, P=parallel forcer phases

⁽²⁾ Reduce continuous stall force to 89% at 40°C ambient

⁽³⁾ Based on a moving thrust rod with 33mm stroke and no payload

⁽⁴⁾ Based on a moving thrust rod with triangular move over maximum stroke and no payload

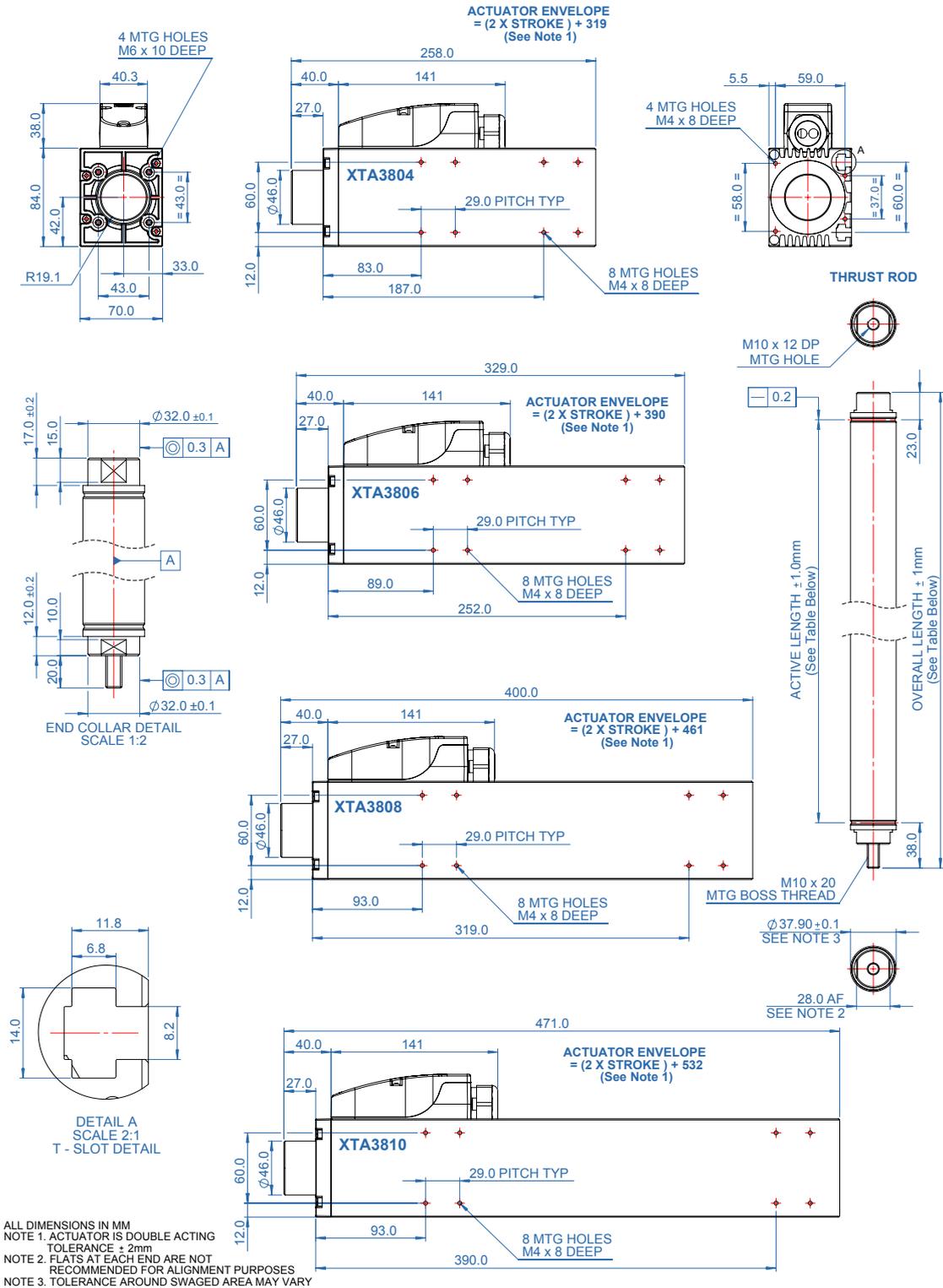
THERMAL SPECIFICATIONS

FORCER TYPE	3804	3806	3808	3810	units
Maximum phase temperature	100	100	100	100	°C
Thermal resistance R _{th} _{phase-housing}	0.23	0.16	0.13	0.11	°C/Watt
With 25 x 25 x2.5cm heatsink plate					
Power dissipation @ 25°C ambient	89.3	110.3	127.1	144.2	Watt
Thermal resistance R _{th} _{housing-ambient}	0.61	0.52	0.46	0.41	°C/Watt
Without heatsink plate					
Power dissipation @ 25°C ambient	68.2	89.3	107.0	123.0	Watt
Thermal resistance R _{th} _{housing-ambient}	0.87	0.68	0.57	0.50	°C/Watt
Thermal time constant	1677	1798	1924	2056	s

MECHANICAL SPECIFICATIONS

FORCER TYPE	3804	3806	3808	3810	units
Maximum stroke	318	318	318	318	mm
Forcer mass (excluding thrust rod and cable)	2.75	3.75	4.75	5.75	kg
Thrust rod mass/metre	8.3	8.3	8.3	8.3	kg/m

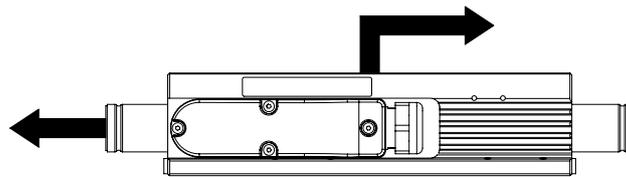
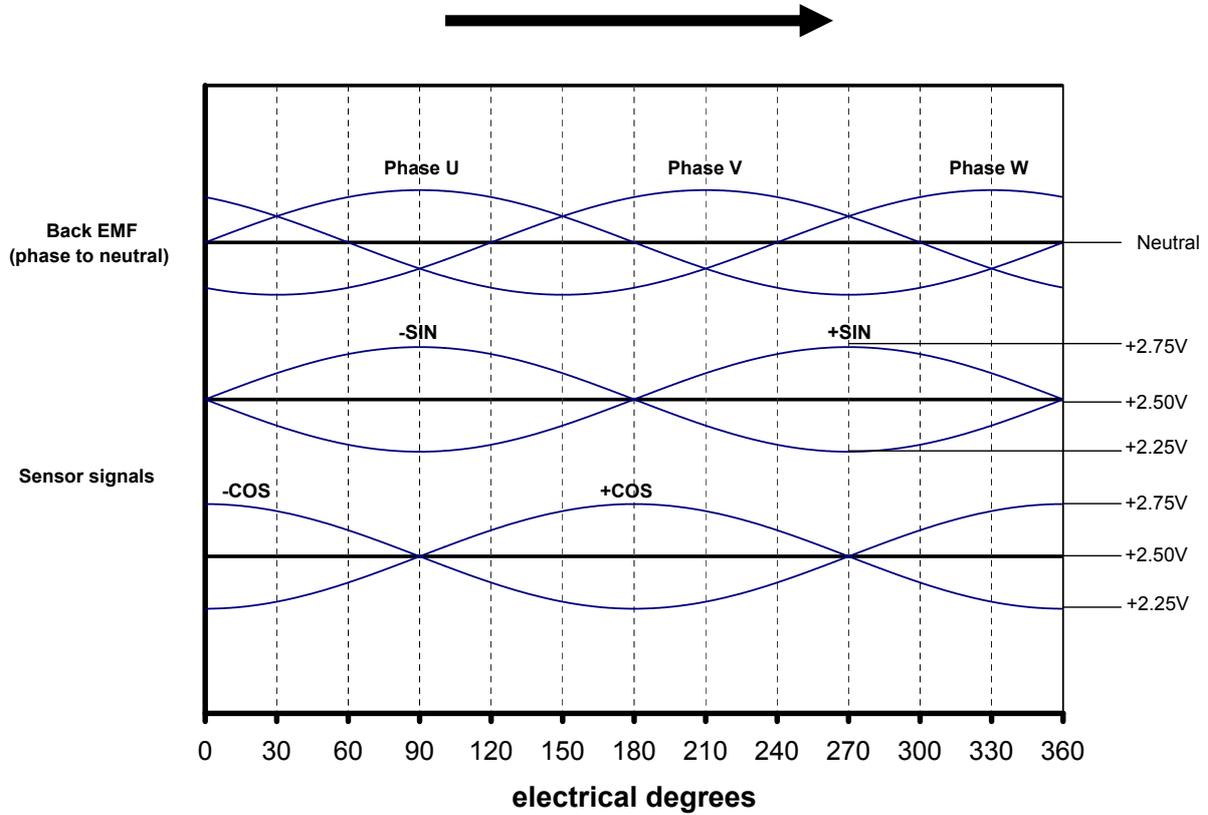
OUTLINE DRAWINGS



Stroke (mm)	3804		3806		3808		3810	
	OVERALL	ACTIVE	OVERALL	ACTIVE	OVERALL	ACTIVE	OVERALL	ACTIVE
33	350	291	421	362	493	434	564	505
69	386	327	457	398	528	469	599	540
104	421	362	493	434	564	505	635	576
140	457	398	528	469	599	540	671	612
176	493	434	564	505	635	576	706	647
211	528	469	599	540	671	612	742	683
247	564	505	635	576	706	647	778	719
282	599	540	671	612	742	683	813	754
318	635	576	706	647	778	719	849	790

POSITION SENSOR

The position sensor outputs analogue, differential sine and cosine signals for providing position feedback. Shown below are the relationships between forcer phase back EMF and position sensor outputs for one direction of motion (as shown by arrows). It should be noted that +SIN or -SIN is always in phase with forcer phase U. For the motion shown, -SIN is in phase with forcer phase U. For motion in the opposing direction +SIN is in phase with forcer phase U.



SPECIFICATION	VALUE	units
Output signal period	71.2	mm
Signal amplitude (between +/- signals)	1	Vpk-pk
Output current	± 10	mA
Supply voltage	5 ± 0.25	Vd.c.
Supply current (output current=0)	15 ± 5	mA
Resolution ⁽¹⁾	20	micron
Position repeatability ⁽²⁾	± 20	micron
Absolute accuracy ⁽³⁾	± 400	micron

Notes: -

⁽¹⁾ Dependent on amplifier

⁽²⁾ Dependent on amplifier. Under constant operating conditions. Self-heating of the forcer will cause expansion in the thrust rod during the initial warm up period. In high duty applications (corresponding to an internal forcer temperature of 80°C) a 1 metre thrust rod will expand typically by 250 microns.

⁽³⁾ Maximum error over 1 metre under constant operating conditions.

FORCER OVER TEMPERATURE SENSOR



It is strongly recommended that the forcer over-temperature sensor is connected to the drive amplifier or servo controller **at all times** in order to reduce the risk of damage to the forcer due to excessive temperatures.

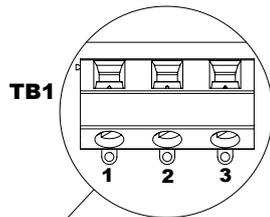
Protection is provided by three positive temperature coefficient (PTC) thermistors embedded in the forcer phases. As the forcer phase temperature approaches 100°C, the PTC thermistors exhibits a sharp increase in electrical resistance. This change in resistance can be detected by circuitry within the drive amplifier or servo controller and used to reduce or disable the output of the drive amplifier in order to protect the forcer.

SPECIFICATION	VALUE	units
Resistance in the temperature range -20°C to +70°C	60 to 750	Ohms
Resistance at 85°C	≤1650	Ohms
Resistance at 95°C	≥3990	Ohms
Resistance at 105°C	≥12000	Ohms
Maximum continuous voltage	30	Vd.c.

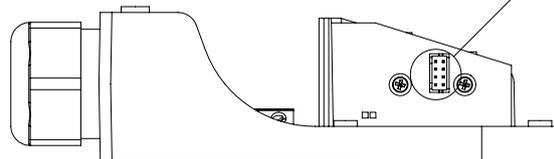
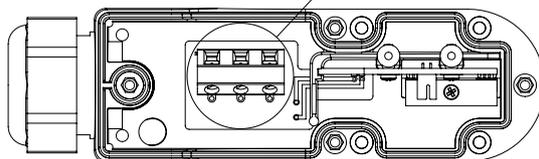
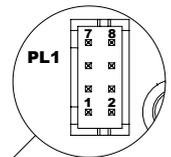
FORCER ELECTRICAL CONNECTIONS

Connections are made within the termination box.

PIN NUMBER	FUNCTION
1	Phase U
2	Phase V
3	Phase W
Chassis	Earth/Screen



PIN NUMBER	FUNCTION
1	+SIN
2	-SIN
3	+COS
4	-COS
5	+5Vd.c.
6	0V
7	+TH (Thermistor)
8	-TH (Thermistor)



CABLE TYPE

The XTA has two separate cables providing connections for forcer power and position sensor. There are two cable types available with option S being supplied as standard. Both cable types are available in 3 metre or 5 metre lengths.

Option S cables are flexible but are not intended for continuous flex or energy chain applications.

OPTION S SPECIFICATION	POWER	SENSOR
Overall diameter (nominal)	8.2mm	7.8mm
Outer jacket material	PVC	PVC
Number of conductors	4	4 x twisted pair
Size of conductors	1.5mm ² (16 AWG)	0.14mm ² (26AWG)
Screened / Unscreened	Screened	Screened
Minimum bending radius - fixed routing	41mm	40mm
Operating temperature - fixed routing	-40°C to +90°C	-40°C to +70°C

Option R cables are suitable for continuous flex or energy chain applications.

OPTION R SPECIFICATION	POWER	SENSOR
Overall diameter (nominal)	7.6mm	7.8mm
Outer jacket material	PUR	PVC
Number of conductors	4	4 x twisted pair
Size of conductors	1.5mm ² (16 AWG)	0.14mm ² (26AWG)
Screened / Unscreened	Screened	Screened
Minimum bending radius - flexible routing	38mm	58mm
Operating temperature - flexible routing	-40°C to +80°C	+5°C to +70°C
Operating temperature - fixed routing	-40°C to +80°C	-40°C to +70°C

CABLE TERMINATION

The XTA cable is available with five termination options. **Option F** has the wire ends stripped and solder tinned ready for termination. All other options are terminated with connectors that plug directly into the desired amplifier. The connections for all options are shown below: -

SENSOR FUNCTION	D-(XTL-S)	M-(XSJ-S)	X-(XSL)	F-Flying leads	P-(Compax 3)
+SIN	14	1	16	Blue	8
-SIN	13	11	17	Black/Blue	7
+COS	12	2	18	White	12
-COS	11	12	19	Black/White	11
+5Vd.c.	4	17	3	Red	2, 4
0V	5	7	2	Black/Red	1, 15
+TH (Thermistor)	10	20	14	Green	5
-TH (Thermistor)	15	14	15	Black/Green	10
SCREEN	1+ shell	1+ shell	1+ shell	SCREEN	shell
Connector type	15-way high density D	20-way 2.54mm Mini Mate	20-way 1.27mm mini D ribbon	-	15-way high density D
Amplifier connection	J8	J6	J8	-	X13
POWER FUNCTION					
Forcer phase U	4	4	4	Black <u>1</u>	1
Forcer phase V	3	3	3	Black <u>2</u>	2
Forcer phase W	2	2	2	Black <u>3</u>	3
Earth (forcer body)	1	1	1	Green/Yellow	4
SCREEN	1	1	1	SCREEN	Amplifier case
Connector type	4-way 5mm pluggable terminal	4-way 5mm pluggable terminal	4-way 5mm pluggable terminal	-	6-way 7.62mm pluggable terminal
Amplifier connection	J2	J2	J2	-	X3

ENVIRONMENT

The XTA is intended for use in an environment within the following conditions: -

SPECIFICATION	VALUE
Operating temperature	0°C to +40°C
Storage temperature	-25°C to +70°C
Ingress protection	IP67
Altitude (above mean sea level)	1000m
Overvoltage category	II
Pollution degree	2
EMC	light industrial

In addition, the STA is available with two environmental coating options. **Option S** has the forcer body coated with a 25 micron layer of black anodise that is suitable for general use. **Option H** has the forcer body coated with a 90 micron layer of hard natural anodise that is suitable for harsher environments.

ORDER CODES

Actuator

XTA38 - - -

Forcer
04, 06, 08, 10

Winding
S - Series
P - Parallel

Stroke
033, 069, 104, 140, 176,
211, 247, 282, 318
Stroke in mm

Environment
S - Standard
H - Harsh

Cable Termination
D - Copley Xenus (XTL-S)
M - Copley Xenus Micro Panel (XSJ-S)
X - Copley Xenus (XSL)
F - Flying leads
P - Parker Compax 3

Cable Length
03 - 3 metre
05 - 5 metre

Cable Type
S - Non-Robotic
R - Robotic

Spare forcer only (with cable)

XTS38 - -

Forcer
04, 06, 08, 10

Winding
S - Series
P - Parallel

Environment
S - Standard
H - Harsh

Cable Termination
D - Copley Xenus (XTL-S)
M - Copley Xenus Micro Panel (XSJ-S)
X - Copley Xenus (XSL)
F - Flying leads
P - Parker Compax 3

Cable Length
03 - 3 metre
05 - 5 metre

Cable Type
S - Non-Robotic
R - Robotic

Spare forcer only (without cable)

XTS38 - - **N**

Forcer
04, 06, 08, 10

Winding
S - Series
P - Parallel

Environment
S - Standard
H - Harsh

Spare thrust rod only

TRS38 -

Forcer

04, 06, 08, 10

Stroke

033, 069, 104, 140, 176,
211, 247, 282, 318

Stroke in mm